Lecture 3. Variational Bayes

Introduction to Bayesian Statistical learning

20.03.2023-24.03.2023. Instructors: Alina Bazarova, Sebastian Starke, Steve Schmerler. Technical issues: Alexandre Strube

Analytic Variational Bayes (slightly heavier on the math)

Formula for posterior distribution (reminder)

$$p(\theta \mid X) = \frac{p(\theta)p(X \mid \theta)}{\int_{\mathbb{R}} p(\theta)p(X \mid \theta)d\theta} = \frac{p(X, \theta)}{\int_{\mathbb{R}} p(\theta)p(X \mid \theta)d\theta}$$

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Assume there is a distribution density function $q(\theta)$ which is in turn parametrised by a series of hyper-parameters.

Free energy and Kullback-Leibler divergence

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Note, that KL divergence is always ≥ 0 and hence $\log p(X) \geq \int q(\theta) \log \frac{p(X,\theta)}{q(\theta)} d\theta$

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Note, that KL divergence is always ≥ 0 and hence $\log p(X) \geq \int q(\theta) \log \frac{p(X,\theta)}{q(\theta)} d\theta$

Moreover, $\int q(\theta) \log \frac{q(\theta)}{p(\theta \mid X)} d\theta = \int q(\theta) \log q(\theta) d\theta - \int q(\theta) \log p(\theta \mid X) d\theta$ **measure of how close** $q(\theta)$ **and** $p(\theta \mid X)$ **are**

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Hence **maximising free energy** is equivalent to **minimising KL divergence**

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The key property of q_{θ_i}:

$$\log q(\theta_i) \propto \int q_{\theta_{-i}}(\theta_{-i}) p(X, \theta) d\theta_{-i} \qquad q_{\theta_{-i}}(\theta_{-i}) = \prod_{j \neq i} q_{\theta_j}(\theta_j)$$

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The proof of the above stems from the calculus of variations.

Sketch of the proof

We need to maximise free energy $F = \int q(\theta) \log \frac{p(X, \theta)}{q(\theta)} d\theta$ with respect to each factorised $q_{\theta_i}(\theta_i)$

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From variational calculus this is equivalent to solving: $\frac{\partial}{\partial q_{\theta_i}(\theta_i)} \int q(\theta) \log \frac{p(X,\theta)}{q(\theta)} d\theta_{-i} = 0$

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$$\frac{\partial}{\partial q_{\theta_i}(\theta_i)} \int q(\theta) \log \frac{p(X,\theta)}{q(\theta)} d\theta_{-i} = 0 \text{ , recall } q(\theta) = \prod_i q(\theta_i)$$

use differentiation by parts

$$\int q_{\theta_{-i}}(\theta_{-i}) \log p(X,\theta) d\theta_{-i} - \int q_{\theta_{-i}}(\theta_{-i}) \log q(\theta_{-i}) d\theta_{-i} - \int q_{\theta_{-i}}(\theta_{-i}) \log q(\theta_i) d\theta_{-i} + const = 0$$

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$$\log q(\theta_i) \propto \int q_{\theta_{-i}} \log p(X,\theta) d\theta_{-i} \blacksquare$$

Algorithm (Mean field variational Bayes for 2 parameters θ_1, θ_2)

1. Initialise $q(\theta_1)$

2. Given $q(\theta_1)$ update $q(\theta_2)$ using $\log q(\theta_2) \propto \int \log p(X, \theta) q(\theta_1) d\theta_1$

3. Given $q(\theta_2)$ update $q(\theta_1)$ using $\log q(\theta_1) \propto \int \log p(X, \theta) q(\theta_2) d\theta_2$

4. Iterate until stopping condition is met.

Example: a single Gaussian

Assume we draw measurements $y = (y_1, \ldots, y_n)$ from a Gaussian distribution with mean μ and precision β: $P(y_i \mid \mu, \beta) = \left(\frac{\beta}{2\pi}\right)^{\frac{1}{2}} e^{-\frac{\beta}{2}(y_i - \mu)^2}$

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Recall $q(\mu) \sim N(m, \nu)$ and hence $m = \frac{m_0 + \nu_0 bcs_1}{1 + N\nu_0 bc}$ and $\nu = \frac{\nu_0}{1 + N\nu_0 bc}$ where $s_1 = \sum_n y_n$

Update on β

We apply a similar procedure to derive an update on β.

$$\log q(\beta) = \int Lq(\mu)d\mu = \int LN(\mu, m, \nu)d\mu = \left(\frac{N}{2} + c_0 - 1\right)\log\beta + \frac{\beta}{b_0} - \frac{\beta}{2}\int \sum_n (y_n - \mu)^2 N(\mu, m, \nu)d\mu + const\{\beta\}$$

$\log q(\beta) = \left(\frac{N}{2} + c_0 - 1\right)\log\beta - \left(\frac{1}{b_0} + \frac{X}{2}\right)\beta$, where X is the integral above:

$$X = \frac{1}{2}\int (s_2 - 2\mu s_1 + \mu^2)N(\mu, m, \nu)d\mu = \frac{1}{2}s_2 - 2s_1 m + N(m + \nu^2), \text{ where } s_2 = \sum_n y_n^2$$

Hence, $\frac{1}{b} = \frac{1}{b_0} + \frac{X}{2}$ and $c = \frac{N}{2} + c_0$.

We can now proceed in an iterative procedure (fix β, update μ and the other way round until necessary)!

Jupyter notebook avb_gaussian

Non-linear models and convergence issues

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Convergence.

- Convergence of VB is guaranteed since it is a generalisation of Expectation Maximisation algorithm

- As soon as we use Taylor approximation, the theory breaks down, and convergence becomes more empirical: e.g. monitoring free energy F, stop when it reaches maximum

Stochastic Variational Bayes

Recall that the problem we discussed previously is maximising free energy

$$F = \int q(\theta) \log \frac{p(X, \theta)}{q(\theta)} d\theta.$$

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$F \approx \frac{1}{L} \sum_l \log p(X, \theta^l) - \log \frac{q(\theta^l)}{p(\theta^l)}$, where θ^l are drawn from $q(\theta)$

Moreover, $\nabla_\phi F \approx \frac{1}{L} \sum_l \nabla_\phi \left(\log p(X, \theta^l) - \log \frac{q(\theta^l)}{p(\theta^l)} \right)$

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- Large L will give a better approximation, but can be computationally heavy

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Can be even simpler: $q(\theta) \sim N(\theta; \mu, \sigma)$. Generate $\varepsilon \sim N(0,1)$, then $\theta = \mu + \sigma\varepsilon$

How to choose L?

In practice even $L = 1$ can be sufficient, however we need to choose **gradient descent algorithm** which deals with **stochastic optimisation**, e.g. **Adam**

To improve computational efficiency use **mini-batches**: divide data into subsets and performing optimisation on each batch in turn.

Very common technique in the machine learning!

Example: fitting a Gaussian distribution

Assume we draw measurements $y = (y_1, \ldots, y_n)$ from a Gaussian distribution with mean μ and precision β: $P(y \mid \mu, \beta) = \left(\frac{\beta}{2\pi}\right)^{\frac{n}{2}} e^{-\frac{\beta}{2}\sum (y_i - \mu)^2}$.

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Recall $MVN(m, C)$ has a pdf function
$p(x, m, C) = (2\pi)^{-n/2} \mid C \mid^{-1/2} \exp\left((x - m)^T C^{-1} (x - m)\right)$

Free energy

$$\int q(\theta)\log\frac{p(\theta)p(y\,|\,\theta)}{q(\theta)}d\theta \approx -\int q(\theta)\log\frac{q(\theta)}{p(\theta)}d\theta + \frac{1}{L}\sum_{l}\log p(y\,|\,\theta^{l})$$

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$$\int q(\theta)\log\frac{q(\theta)}{p(\theta)}d\theta = \frac{1}{2}\left(Tr(C_0^{-1}C) - \log\left(\frac{|\,C\,|}{|\,C_0\,|}\right) - N + (m - m_0)^{T}C_0^{-1}(m - m_0)\right)$$

Jupyter notebooks svb_gaussian_tf2, svb_biexp_tf2